



Programming Manual

For the

USB RF Switch Matrices



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1- Overview

This programming Manual is intended for customers wishing to create their own interface for Mini-Circuits' USB RF Switch Matrices.

Mini-Circuits offers support for USB Portable Test Equipment (PTE) in Windows® and Linux® Operating Systems, in a variety of programming environments including third-party applications such as LabVIEW® and MATLAB® through .NET assembly and ActiveX® Controls to write your own customized control applications.

Mini-Circuits' CD package Includes: GUI program installation, DLL Objects 32/64 bit, Linux Support, project examples for 3RD party software and Documents. The latest CD version is available for download at http://www.minicircuits.com/support/software_download.html , see Figure 1.

| RF Switch Controller | | | | |
|--------------------------------|---------------|--------------------------|--|--|
| Product Name | Version | Download | Description / Instructions | Models Supported |
| RF Switch Controller - Setup | A9 | Download | RF Switch Controller GUI program for Windows 32/64 bit - Latest Version - Setup. | USB-1SPDT-A18 (XL) USB-2SPDT-A18 (XL) USB-3SPDT-A18 (XL) USB-4SPDT-A18 (XL) |
| RF Switch Controller - CD | A9 | Download | Latest Version of the entire Switch Controller CD: GUI program, DLL COM Objects 32/64 bit, Linux Support and Documents. When extracting the files after download, keep the folder names. | |
| MCL_RF_Switch_Controller.dll | Dec 06, 2011 | Download | Dll - ActiveX com object file. Registering to Windows is required. Recommended for 32 bit programming. | |
| mcl_RF_Switch_Controller64.dll | Dec 06, 2011 | Download | Dll - .NET Class Library. Recommended for 64/32 bit programming. | |
| Programming Manual | Apr. 16, 2012 | Download | PDF File: Detailed Guide for Programmers. | |
| Project Examples | Apr. 16, 2012 | Download | Projects Examples for several Programming environments such as: VB6, VB.NET, C#, C++, Delphi, LabView, Matlab, LINUX. | |
| | | | When extracting the Zip file after download: keep the folder names. | |

Figure 1 – Download Screen

2 - Operating in a Windows® Environment 32/64Bits OS with USB HID Support

The DLL Object (Dynamic Link Library) - Concept:

Dynamic **L**ink **L**ibrary is Microsoft's implementation of the shared library concept in the Microsoft Windows® environment.

DLLs provide a mechanism for shared code and data, allowing a developer of shared code/data to upgrade functionality without requiring applications to be re-linked or recompiled.

Mini-Circuits' CD package provides DLL Objects in order to allow your own Software Application to interface with the functions of the Mini-Circuits' USB Portable Test Equipment hardware, see Figure 2.

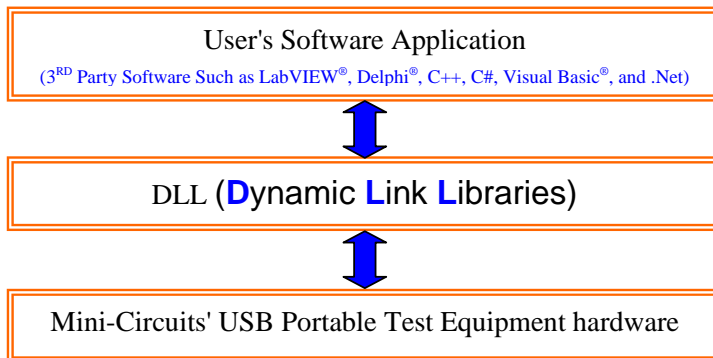


Figure 2 – DLL Interface

Mini-Circuits' provides two DLLs files:

1. ActiveX® com object - *MCL_RF_Switch_Controller.dll* → Click to download
http://www.minicircuits.com/support/software_download.html
ActiveX® com object can be used in any programming environment that supports ActiveX® objects - third party COM (Component Object Model) compliant application. The ActiveX® DLL should be registered using RegSvr32 (see pages 5 and 6 - Register an ActiveX® DLL).
2. .NET Class Library - *MCL_RF_Switch_Controller64.dll* → Click to download
http://www.minicircuits.com/support/software_download.html
.NET object – a logical unit of functionality that runs under the control of the .NET

2.1 - Software supported by ActiveX® and .NET Class Library

| <i>MCL_RF_Switch_Controller.dll</i> - ActiveX® com object | <i>MCL_RF_Switch_Controller64.dll</i> - .NET Class Library |
|--|--|
| <p>Instructions</p> <ul style="list-style-type: none"> For 32bit Windows OS, copy MCL_RF_Switch_Controller.dll to windows\system32 folder For 64bit Windows OS, copy MCL_RF_Switch_Controller.dll to windows\SysWOW64 folder Register the DLL, see instructions below <p>Visual Studio 6 (VC++, VB®) NI LabVIEW® 8.0 or newer MATLAB® 7 or newer Delphi® Borland C++ Agilent VEE® Python</p> | <p>Instructions</p> <ul style="list-style-type: none"> For 32bit Windows OS copy MCL_RF_Switch_Controller64.dll to windows\system32 folder For 64bit Windows OS copy MCL_RF_Switch_Controller64.dll to windows\SysWOW64 folder DLL Registry is not required <p>NI CVI NET (VC++, VB.net, C# 2003,2005,2008,2010) NI LabVIEW® 2009 or newer MATLAB® 2008 or newer Delphi® Borland C++</p> |

* Additional 3RD party software are supported, contact Mini-Circuits for details.

How to register MCL_RF_Switch_Controller.dll, 32-bit DLL, on a 32-bit Windows OS?

Open the Run Command from the Start Menu and type
regsvr32 c:\windows\system32\mcl_RF_Switch_Controller.dll

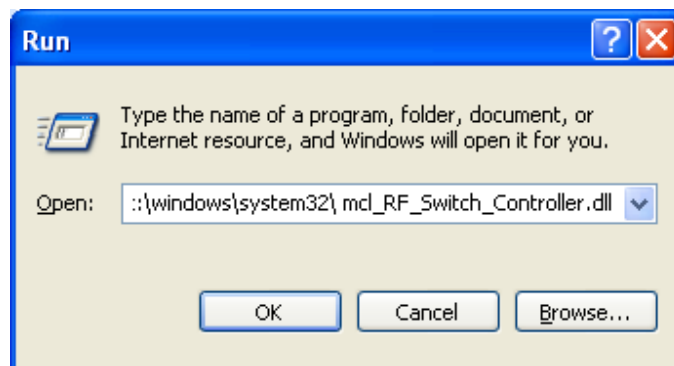
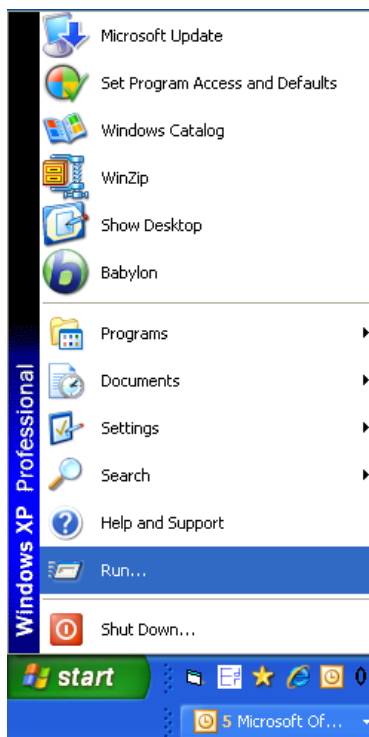


Figure 3 – Run Command

How to register MCL_RF_Switch_Controller.dll, 32-bit DLL on a 64-bit Windows OS?

- Run the Command Prompt as Administrator, see figure 4

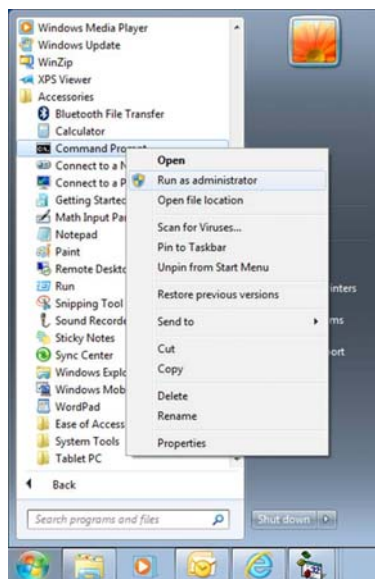


Figure 4 – Command Prompt

- Type `regsvr32 c:\windows\syswow64\mcl_rf_Switch_Controller.dll`, see figure 5

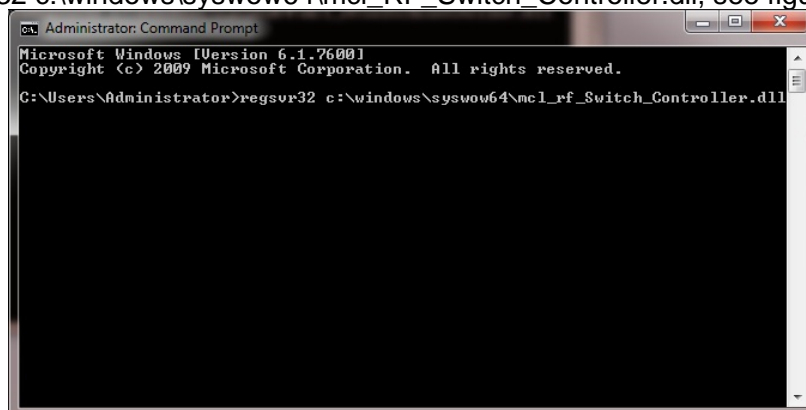


Figure 5 – Type command

- Click Enter, see figure 6.

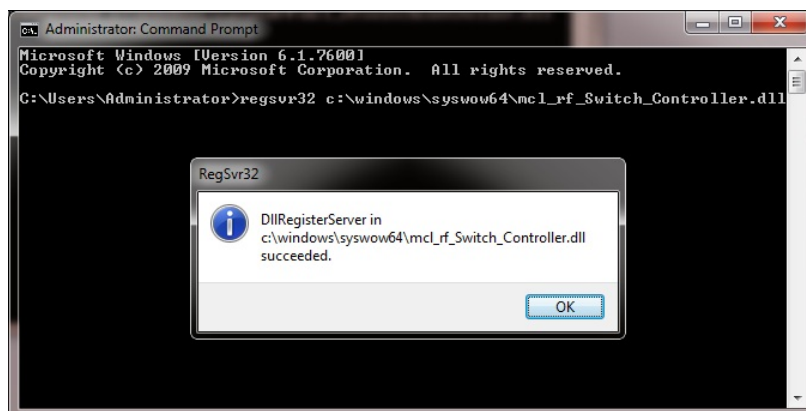


Figure 6 – Registration succeeded

2.2 - DLL Structure (both *MCL_RF_Switch_Controller.dll* and *MCL_RF_Switch_Controller64.dll*)

DLLs Functions *MCL_RF_Switch_Controller.dll* and *MCL_RF_Switch_Controller64.dll*

1. **Int** Connect(Optional String SN)
2. **Int** ConnectByAddress(Optional Short Address)
3. **Void** Disconnect()
4. **Int** GetSwitchesStatus(Int StatusRet)
5. **Int** Read_Model_Name(String ModelName)
6. **Int** Read_SN(String SN)
7. **Int** Set_Switch(String SwitchName, Int Val)
8. **Int** Set_SwitchesPort (Byte Val)
9. **Int** Set_Address(Int Address)
10. **Int** Get_Address()
11. **Int** Get_Available_SN_List(String SN_List)
12. **Int** Get_Available_Address_List(String Add_List)
13. **Float** GetDeviceTemperature(Short TSensor)
14. **Int** GetHeatAlarm()

Functions Description:

1. **Int** Connect(Optional String SN)

SN parameter is needed when more than one Switch Box is connected to the computer.
SN is the Serial Number of the Switch Box and can be ignored if using only one box.

2. **Int** ConnectByAddress(Optional Short Address)

Address parameter represents the Address of the Switch Box. The address can be any integer number from 1 to 255 and can be changed by the SetAddress function (function 9).

Address parameter is needed if more than one Switch Box is connected to PC. In this case the connection to the Switch Box is by Address instead of SN. This is an alternative to Function 1 (connect by SN).

3. **Void** Disconnect()

Close connection to the Switch Box. It is strongly recommended to use this function to disconnect the device before ending the program.

Shutting down the program without disconnecting the device may result in connection problem to the device. To resolve the issue shut down the program, then unplug the Switch Box from the computer and plug it back in before starting the program again.

4. **Int** GetSwitchesStatus(Int StatusRet)

StatusRet - Contains the status for each switch in the box.

The LSB bit represents switch "A" then "B" etc...

For example: if StatusRet=12 (B00001100) - Switch C and D are ENERGIZED, all others DE-ENERGIZED.

The function returns a non-zero value upon success.

5. **Int** Read_Model_Name(String ModelName)

ModelName - Contains the Switch Box Model Name

The function returns a non-zero value upon success.

6. **Int** Read_SN(String SN)

SN- Contains the Switch Box Serial Number

The function returns a non-zero value upon success.

7. **Int** Set_Switch(String SwitchName, Int Val)

SwitchName – Contains the switch letter can be "A", "B", "C" or "D" (model must have the switch designated)

Val - Contains 0 for DE-ENERGIZED any other value (1 to 255) for ENERGIZED.

The function returns a non-zero value upon success.

8. **Int** Set_SwitchesPort (Byte Val)

This function allows you to set all switches in the Matrix to the desired state with a single command.

Each bit in the "Val" parameter controls the state of a different switch ('0'=De-Energized, '1'=Energized). LSB controls Switch A.

For example Set_Switches(5) will set switch A and C to Energized, and all others De-Energized. (Decimal 5 is Binary 00000101: bits A and C are set to "1"=Energized).

The function returns a non-zero value upon success.

9. **Int** Set_Address(Int Address)

Set the address of the unit. The address can be any number in the 1 to 255 range.

The function returns a non-zero value upon success.

10. **Int** Get_Address()

The function returns the device address.

If fails - Returns 0.

11. **Int** Get_Available_SN_List(String SN_List)

SN_List contains a list of all available Serial Numbers (separated by a single space character):
[SN1] [SN2] [SN3] [SN4]....

The function returns a non-zero value upon success.

12. **Int** Get_Available_Address_List(String Add_List)

Add_List contains a list of all available addresses (separated by a single space character).

The function returns a non-zero value upon success.

13. **Float** GetDeviceTemperature(Short TSensor)

Get the device temperature.

The device may have 2 internal temperature sensors.

Tsensor =1 for sensor number 1 or 2 for sensor no 2.

The function returns the temperature value in Celsius.

14. **Int** GetHeatAlarm()

The function returns 1 if the temperature of either of the temperature sensors exceeds 50° Celsius, (usually the temperature should not exceeded this value), else return 0.

2.3 - Sample code

The CD package also includes a number of sample programs developed to show you how to write your own programs. The sample programs were developed in Visual C++[®], Visual Basic[®], C# and LabVIEW[®]. The sample programs provide an excellent starting point to write your own applications.

The complete project samples are available on the CD or at:

http://www.minicircuits.com/support/software_download.html

3 - Operating in a Linux® Environment 32/64Bits OS with USB HID Support

To open a connection to the RF Switch Box, Vendor ID and Product ID are required:

- Mini-Circuits Vendor ID is: 0x20CE
- USB RF Switch Box Product ID is: 0x22

The communication with the sensor is done by USB Interrupt.
The transmitted and received buffer sizes are 64 Bytes.

Transmit Array should be 64 bytes [Byte 0][Byte1][Byte2].....[Byte 63]
Receive Array contains 64 bytes [Byte 0][Byte1][Byte2].....[Byte 63]

Commands List:

| # | Description | Command Code – Byte[0] | Additional Transmitted Bytes |
|---|---|------------------------|--|
| 1 | Get device Model Name | 40 | -- |
| 2 | Get device Serial Number | 41 | -- |
| 3 | Set Switch A (ENERGIZED or DE-ENERGIZED) | 1 | Byte[1] – 0 DE-ENERGIZED or 1 ENERGIZED |
| 4 | Set Switch B (ENERGIZED or DE-ENERGIZED) | 2 | Byte[1] – 0 DE-ENERGIZED or 1 ENERGIZED |
| 5 | Set Switch C (ENERGIZED or DE-ENERGIZED) | 3 | Byte[1] – 0 DE-ENERGIZED or 1 ENERGIZED |
| 6 | Set Switch D (ENERGIZED or DE-ENERGIZED) | 4 | Byte[1] – 0 DE-ENERGIZED or 1 ENERGIZED |
| 7 | Set all switches | 9 | Byte[1] – see description |
| 8 | Get Switches Status | 15 | |

* See detailed description on pages 11 - 13

1. Get Device Model Name

Transmit Array

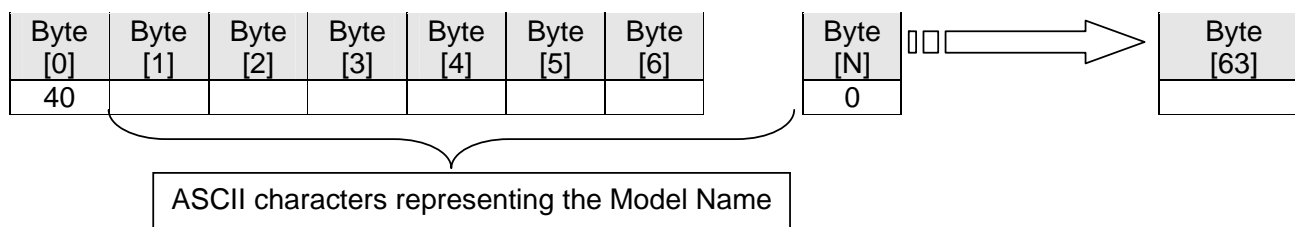
To get the Device Model Name, code number 40 should be sent.

- Byte[0]=40
- Bytes[1] through [63] are NC - Not Care

Received Array

The model name will be returned in the receive array of ASCII characters. End of model name is signified by a 0 value.

- Byte[0]=40
- Byte[1] to the byte before the 0 value = Model Name
- All bytes after the 0 value up to byte [63] contain random values



2. Get Device Serial Number:

Transmit Array

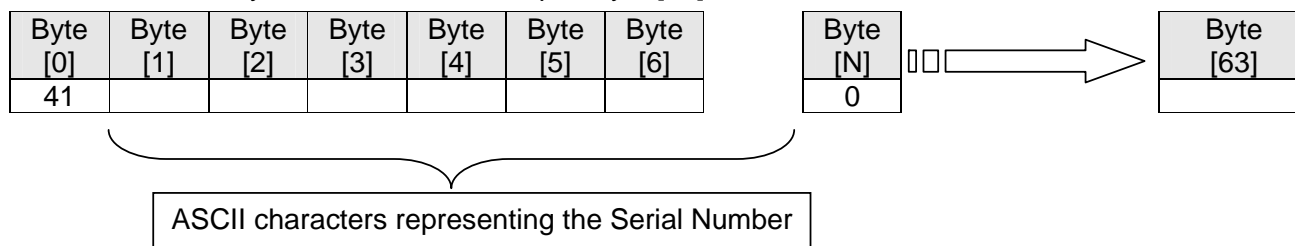
To get the Device Serial Number, code number 41 should be sent

- Byte[0]=41
- Bytes[1] through [63] are NC - Not Care

Received Array

The Serial Number will be returned in the receive array of ASCII characters. End of Serial Number is signified by a 0 value.

- Byte[0]=41
- Byte[1] to the byte before the 0 value= Serial Number
- All bytes after the 0 value up to byte [63] contain random values



3. Set Switch A: Available for all models

Transmit Array

To set Switch A, code number 1 should be sent in Byte[0], and Byte[1] should be 0 for DE-ENERGIZED or 1 for ENERGIZED

- Byte[0]=1
- Byte[1] = 0 for DE-ENERGIZED or 1 for ENERGIZED
- Bytes[2] through [63] are NC - Not Care

Received Array

The returned array of 64 bytes will be as follows:

- Byte[0]=1
- Byte[1] through [63] contain random values

4. Set Switch B: NOT Available for the USB-1SPDT-A18

Transmit Array

To set Switch B, code number 2 should be sent in Byte[0], and Byte[1] should be 0 for DE-ENERGIZED or 1 for ENERGIZED

- Byte[0]=2
- Byte[1] = 0 for DE-ENERGIZED or 1 for ENERGIZED
- Bytes[2] through [63] are NC - Not Care

Received Array

The returned array of 64 bytes will be as follows:

- Byte[0]=2
- Byte[1] through [63] contain random values

5. Set Switch C: NOT Available for the USB-1SPDT-A18 or USB-2SPDT-A8

Transmit Array

To set Switch C, code number 3 should be sent in Byte[0], and Byte[1] should be 0 for DE-ENERGIZED or 1 for ENERGIZED

- Byte[0]=3
- Byte[1] = 0 for DE-ENERGIZED or 1 for ENERGIZED
- Bytes[2] through [63] are NC - Not Care

Received Array

The returned array of 64 bytes will be as follows:

- Byte[0]=3
- Byte[1] through [63] contain random values

6. Set Switch D: Available for the USB-4SPDT-A18 ONLY

Transmit Array

To set Switch D, code number 4 should be sent in Byte[0], and Byte[1] should be 0 for DE-ENERGIZED or 1 for ENERGIZED

- Byte[0]=4
- Byte[1] = 0 for DE-ENERGIZED or 1 for ENERGIZED
- Bytes[2] through [63] are NC - Not Care

Received Array

The returned array of 64 bytes will be as follows:

- Byte[0]=4
- Byte[1] through [63] contain random values

7. Set all switches:

Handles all switches in one command

Transmit Array

- Byte[0]=9
- Byte[1]= Set Switches state(Switch A- is LSB)
- Bytes[2] through [63] are NC - Not Care

Bits used in Byte[1]:

The USB-1SPDT-A18 contains one Switch – bit LSB (0)

The USB-2SPDT-A18 contains two Switches – Bits: LSB (0) =A, 1=B

The USB-3SPDT-A18 contains three Switches – Bits: LSB (0) =A, 1=B, 2=C

The USB-4SPDT-A18 contains four Switches – Bits: LSB (0) =A, 1=B, 2=C, 3=D

For example, to set Switches A, B and C to Energized (1) and Switch D to DE-Energized (0) the following code should be sent:

- Byte[0]=9
- Byte[1]=7

Byte[1] → 00000111=7

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|-------|-------|-------|-------|-----------------|-----------------|-----------------|-----------------|
| | | | | Switch D | Switch C | Switch B | Switch A |
| (MSB) | | | | | | | (LSB) |
| 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 |

Received Array

- Byte[0]=9
- Bytes[1] through [63] contain random values

8. Get Switches Status

Transmit Array

- Byte[0]=15
- Bytes[1] through [63] are NC - Not Care

Received Array

- Byte[0]=15
- Bytes[1]= Switches Status (LSB is for Switch A)
- Bytes[2] through [63] contain random values

3.1 – Sample code

The Linux Folder in the CD package contains the following:

- switch.c example source code using the libhid & libusb libraries to open the USB HID device.

Linux Project Examples are also available on the CD package or can be downloaded at:

http://www.minicircuits.com/support/software_download.html

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